



Powering Innovation That Drives Human Advancement

Model-Based Solution for Embedded Controls of the Future

Christian Schrader
Global Technical Lead Automotive

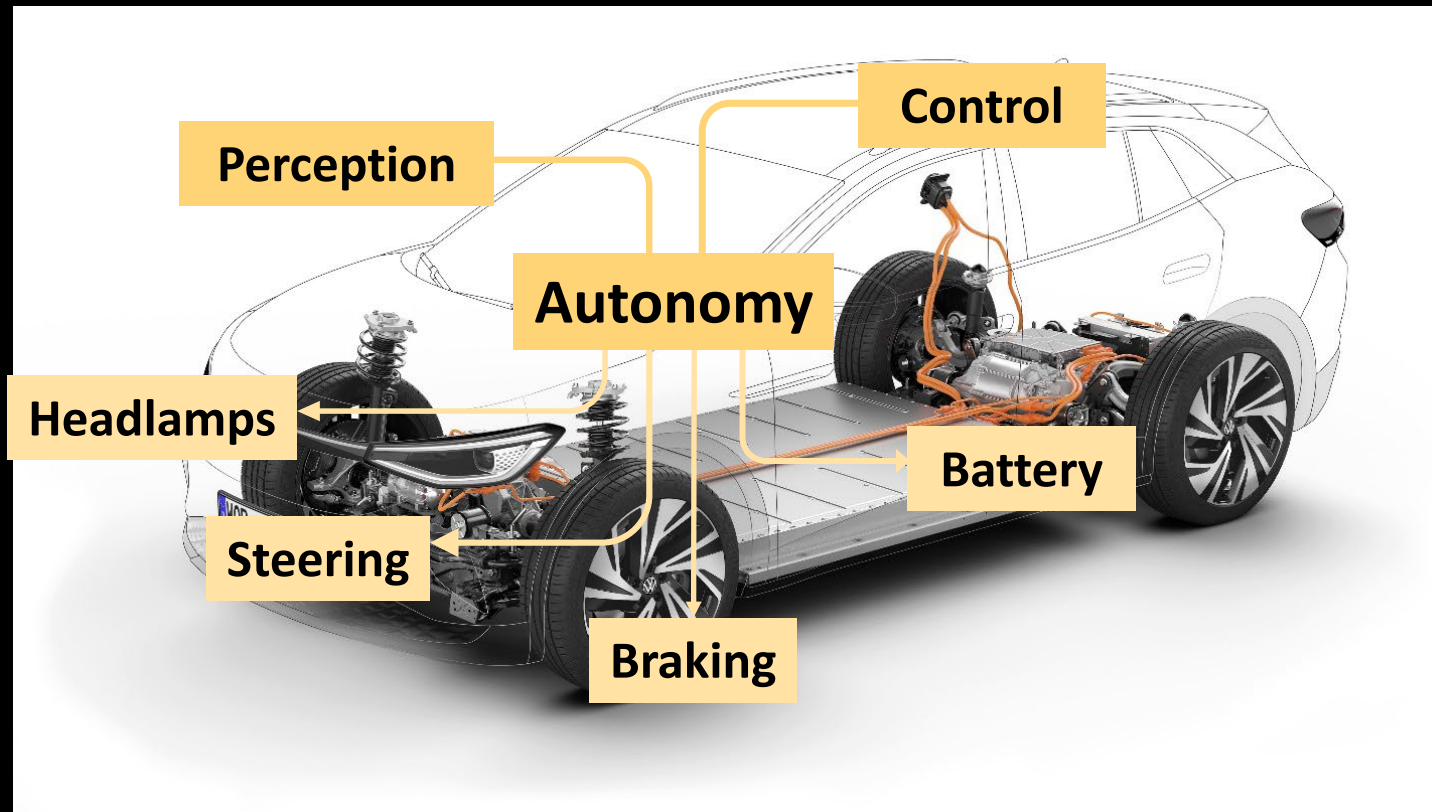
Oct 16, 2024



From Fail-Safe to Fail-Operational Systems: Challenges

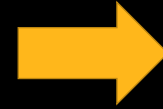
Fail-operational demands driven by automotive autonomy (SAE 3+)

*Autonomy & Electrification as drivers towards higher ASIL
(HW and SW)*



Fail-operational demands driven by automotive autonomy (SAE 3+)

“A **fail-safe system** relies on the human as part of the safety concept to maintain a degraded level of control to be able to stop the vehicle in the event of a failure.”



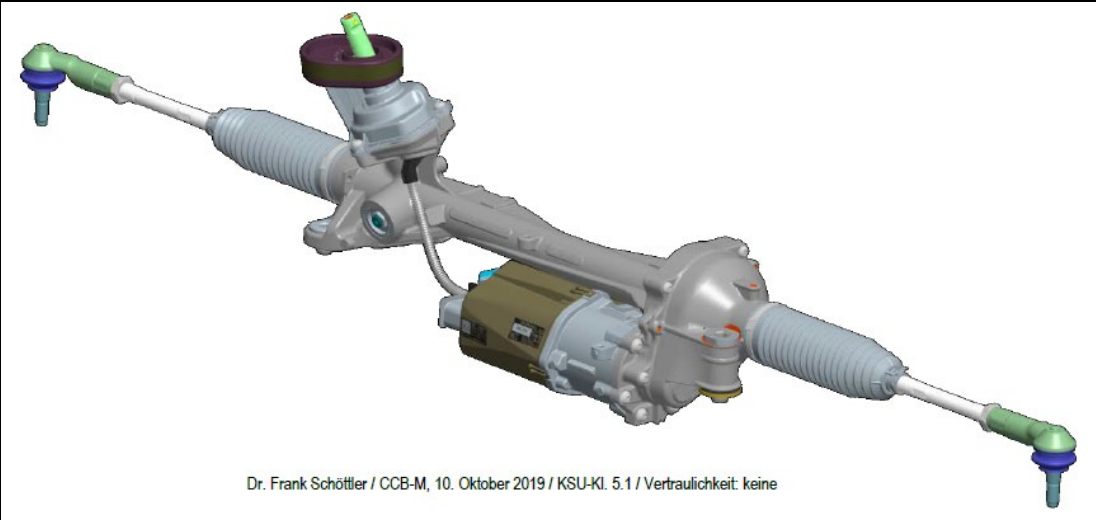
“A **fail-operational system** is designed to maintain normal operation, even in the event of a system fault.”

Previous Gen		Current Gen		Next Gen	
FAIL SAFE		SAFETY AND AVAILABILITY		FAIL OPERATIONAL	
Detect fault Indicate fault to safe state system		Detect fault Indicate fault to safe state system and recover		Detect fault Indicate fault to safe state system	
Stop operation		Continue operation Continue degraded Stop operation		Continue full operation	
0 – No Adas	1 – Feet off	2 – Hands off	3 – Eyes off	4 – Mind off	5 – No driver
Human driver is driving			Upon system request	System is driving	
			Human driver is driving		
Driver support features			Automated driving features		

SAE Levels of
Driving Automation



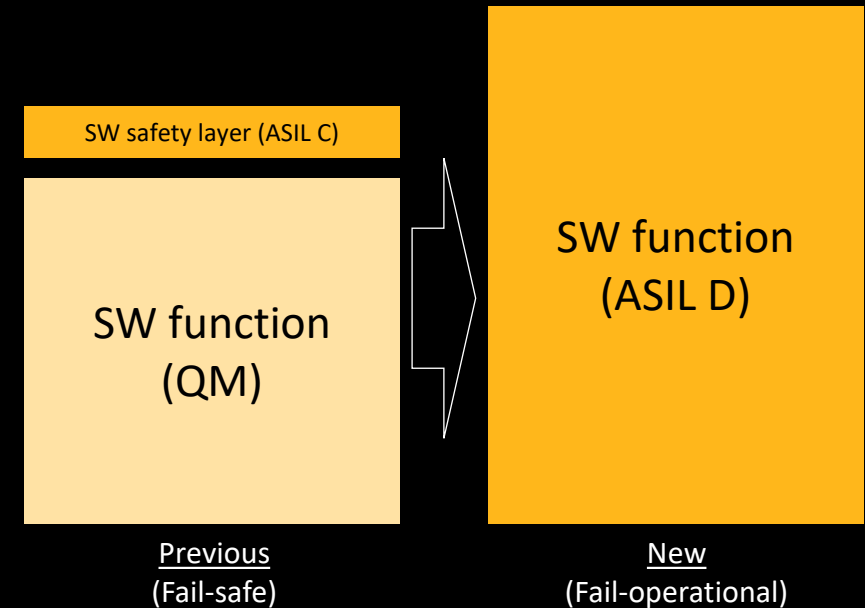
Transition to fail-operational automotive systems



Volkswagen

Customer challenges

- **VW** is developing a **new Electrical Power Steering Platform**
 - SAE **Level 3+** (SAE **Level 2** in previous steering generation)
 - ASIL D fail operational (no ASIL + fail safe in previous steering generation)
- New approaches required to cope with **increased complexity**
 - **Change** in strategy from developing a system with **cut-off mechanism** towards a system **that guarantees availability** demanded by autonomous driving functions
 - Towards full model-based toolchain **from systems to SW level**

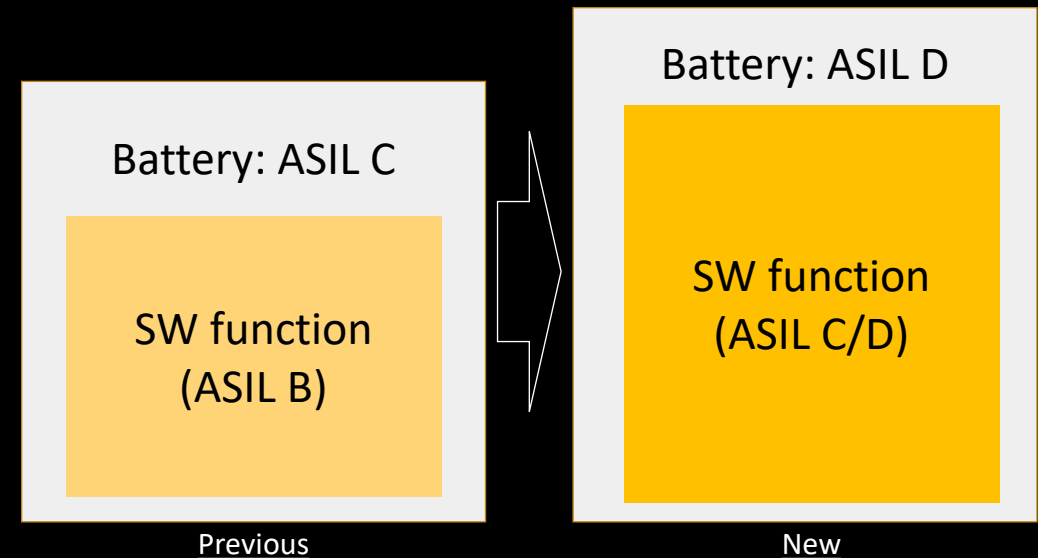


Transition to fail-operational automotive systems

Volkswagen

Customer challenges

- VW is developing **Battery Management System (BMS)** for next generation electric and ADAS/autonomous vehicles
- Toolchain maintenance consumes a significant amount of **engineering bandwidth** every year
 - Version stability, checks on model level and code level for safety violations etc.
- **Autonomous Driving** requirements at the vehicle level trigger a shift from ASIL B to ASIL C and D for the BMS Software
 - Combined with **fail-operational availability** demands
- These requirements trigger increase of **workload in verification and validation, reviews, compliance to A-Spice**





From Fail-Safe to Fail-Operational Systems: Solution

A solution rooted in commercial aerospace and defense (A&D)



*Eurocopter – EC 135/155 Autopilot
DO-178B DAL A Certification (1999)*

Flight Control Systems

- Autopilots
- Air Data and Inertial Reference
- Flight Control / High Lift / Slat&Flaps
- High Lift Hydraulic Control System
- Active

Cockpit & Avionics

- Cockpit Displays
- Head-up Displays
- Flight Management
- Flight Warning
- Navigation, Guidance & Inertial Unit
- On-Board Airport Navigation



*Thales Aerospace – Airbus A350 Cockpit
Display System (1st flight 2013)*



*GE Aviation – LEAP engine FADEC for
Airbus A320 Neo, Boeing 737 Max,
COMAC C919 (1st flight 2016)*

Engine Control Systems

- Engine Control (FADEC)
- Nacelle Controls
- Thrust Reversers
- Electric Engines
- Hydrogen Engines

Control Systems

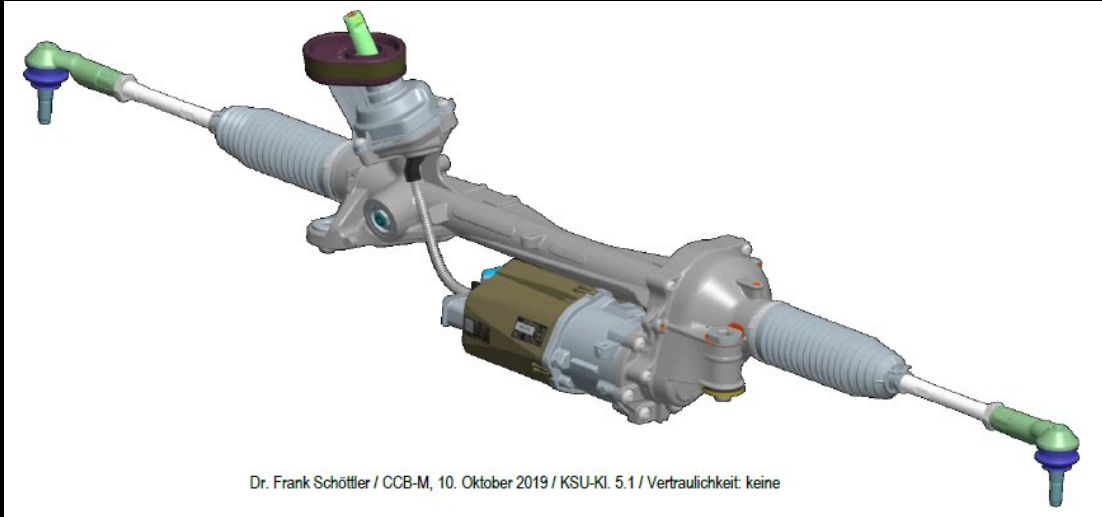
- Fuel Management
- Power Management
- Auxiliary Power Units (APU)
- Anti-Icing
- Braking and Landing Gear
- Hydraulic Controls
- Air & Cabin Controls

All of these systems are fail-operational!



*Meggitt – Brake Control System for
Dassault Aviation Falcon 7X and
Embraer Phenom 100*

... supporting transition to fail-operational automotive systems



Volkswagen

*“Integration time going down from 6 weeks to 2 days.
Testing time going down from 16 weeks to 4 weeks.
System is completely ASIL-D certifiable.”*



Customer challenges

- **VW is developing PPE - a new Electrical Power Steering Platform**
 - SAE Level 3+ (SAE Level 2 in previous steering generation)
 - ASIL D fail operational (no ASIL + fail safe in previous steering generation)
- **New approaches required to cope with increased complexity**
 - Change in strategy from developing a system with **cut-off mechanism** towards a system that **guarantees availability** demanded by autonomous driving functions
 - Towards full model-based toolchain **from systems to SW level**

Key Results with Ansys

- System is completely **ASIL-D certifiable**
 - With fully **ASIL D qualified end-to-end** toolchain: code generation, testing, reporting, Autosar integration
- **Testing and review activities on model level**
 - No **back-to-back** testing, source code reviews
 - Integration time going down from **6 weeks to 2 days**
 - Testing time going down from **16 weeks to 4 weeks**
- **Smooth integration** between requirements management, architecture and functional SW design

... supporting transition to fail-operational automotive systems

Volkswagen

Fast and safe transition from fail-safe and ASIL B battery management SW to fail-operational and ASIL C

Learn More 



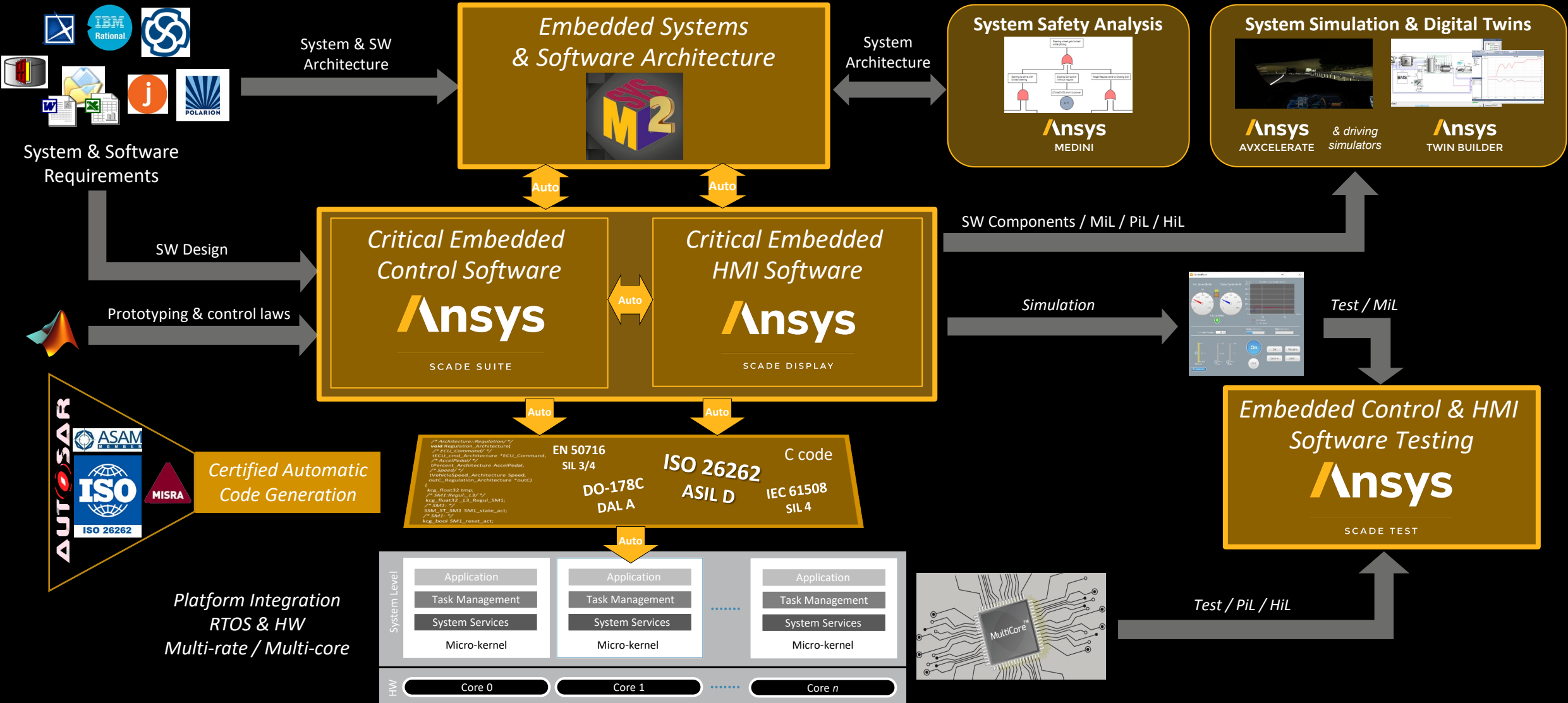
Customer challenges

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- **Autonomous Driving** requirements at the vehicle level trigger a shift from ASIL B to ASIL C for the BMS Software
 - Combined with **fail-operational availability** demands
- These requirements trigger increase of **workload in verification and validation, reviews, compliance to A-Spice** etc.

Key Results with Ansys

- **Suppression of need for in-house verification tools** thanks to trustable ISO 26262-qualified generated code
- Guaranteeing **version stability** in models and code
- Improved validation activities through **fast test execution (x100), including model coverage**
- **In production (ID.3 & ID.4). 20 different projects use SCADE. 100% of BMS SW developed using SCADE.**

SCADE / The reference for Safety-Critical Embedded Software





Qualification level of SCADE Tools

ZERTIFIKAT ◆ CERTIFICATE ◆ 認證證書 ◆ СЕРТИФИКАТ ◆ CERTIFICADO ◆ CERTIFICAT



CERTIFICATE

No. Z10 055460 0027 Rev. 00

Holder of Certificate: ANSYS France SAS
15 Place Georges Pompidou
78180 Montigny-le Bretonneux
FRANCE

Certification Mark:



Product: Software Tool for Safety Related Development

Model(s): Code Generator SCADE Suite KCG 6.6.4

Parameters: The code generator - classified as T3 offline support tool according to IEC 61508-4 / EN 50128 and TCL 3 according to ISO 26262-8 - is qualified for the use in safety-related software development according to IEC 61508, EN 50128 and ISO 26262.
The report AM101878C is a mandatory part of this certificate.

Tested according to: IEC 61508-1:2010 (SIL 3)
IEC 61508-3:2010 (SIL 3)
EN 50128:2011 (SIL 3/4)
EN 50128:2011/A1:2020 (SIL 3/4)
EN 50128:2011/A2:2020 (SIL 3/4)
ISO 26262-8:2018 (ASIL D)

The product was tested on a voluntary basis and complies with the essential requirements. The certification mark shown above can be affixed on the product. It is not permitted to alter the certification mark in any way. In addition the certification holder must not transfer the certificate to third parties. This certificate is valid until the listed date, unless it is cancelled earlier. All applicable requirements of the testing and certification regulations of TÜV SÜD Group have to be complied. For details see: www.tuvsud.com/ps-cert

Test report no.: AM101878C
Valid until: 2028-12-07

Date, 2023-12-13

(Peter Weiß)

Page 1 of 1
TÜV SÜD Product Service GmbH • Certification Body • Ridlerstraße 65 • 80339 Munich • Germany

TUV®

Everyone has something similar to this at first glance!



Multiple SCADE Suite and Display KCG Tool certifications by TÜV

SCADE code generator has been developed according to the highest levels of safety standards



5.3 Conclusion

Safety of **Scade-language** means that the language is scientifically proven to be completely accurate and formally defined. Safe State Machines, formerly expressed by Esterel-language, and Block Diagrams were merged into SCADE 6 language by the extension of LUSTRE-language.

Safety of **generated C/Ada code** means that unsafe C/Ada language constructs are explicitly excluded. It contains no dynamic memory allocation, no pointer arithmetic, and the only loops are bounded loops over delay buffers and over bounded arrays. It also means that the generated code behaviour complies with the model semantics.

Safety of **Code generator KCG** means that the behaviour of the generated C/Ada Code complies with the model semantics of the SCADE model. To avoid deviations between SCADE model and generated C/Ada Code, the development process of ANSYS France underlies the requirements of safety related software standards with respect to fault avoidance.

Safety of **implementation** means that the development tools used for KCG are reliable. The use of ML language and compiler has been assessed according to IEC 61508 SIL3 and EN 50128 SIL3/4. The assessment summary, provided in the technical report, concludes that the ML language and compiler with their restrictions of use are fit for the purpose of developing KCG.

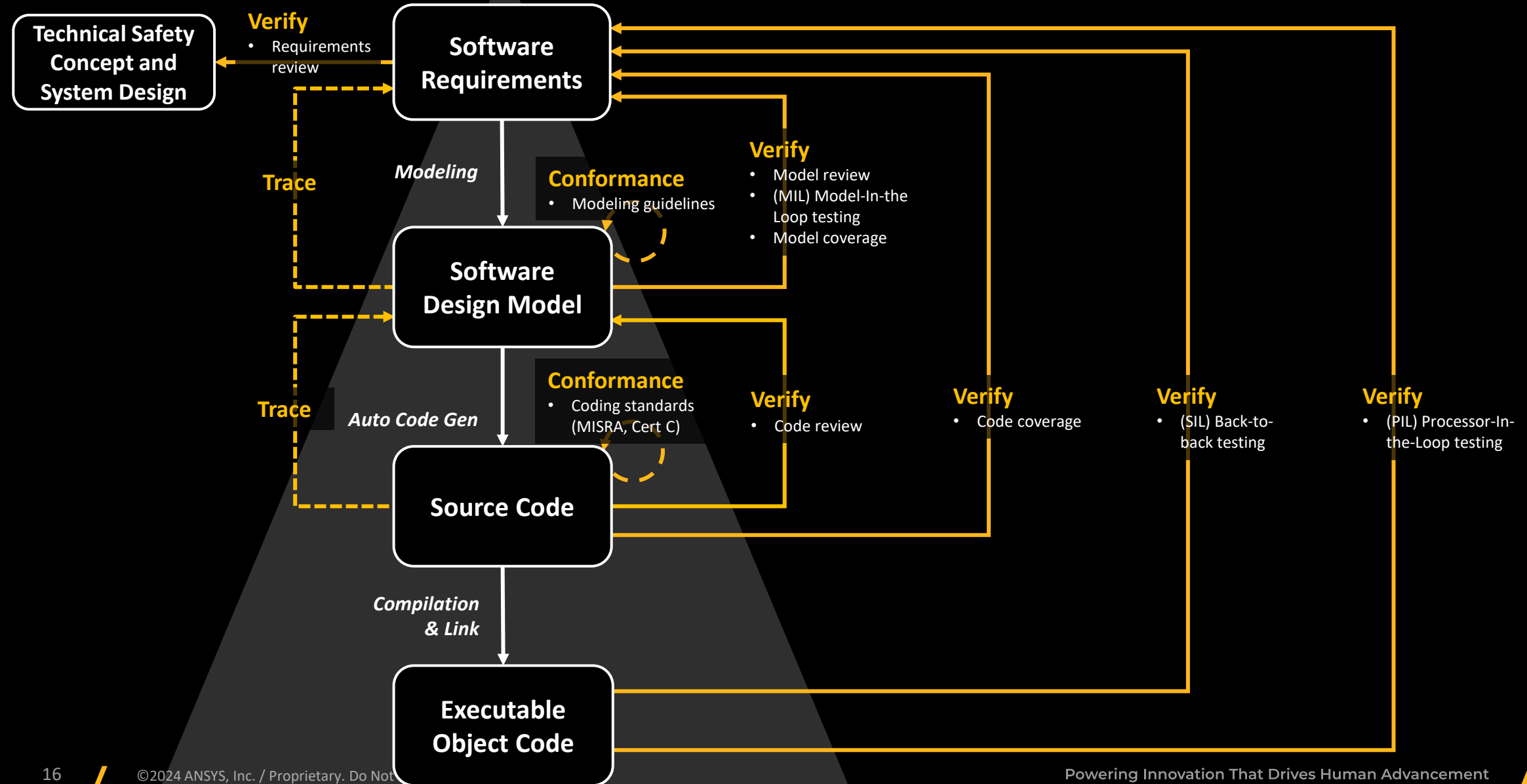
Anslys SCADE is the only tool with this type of certification.

Only full TCL3 certification on the market (code generator + testing and reporting)

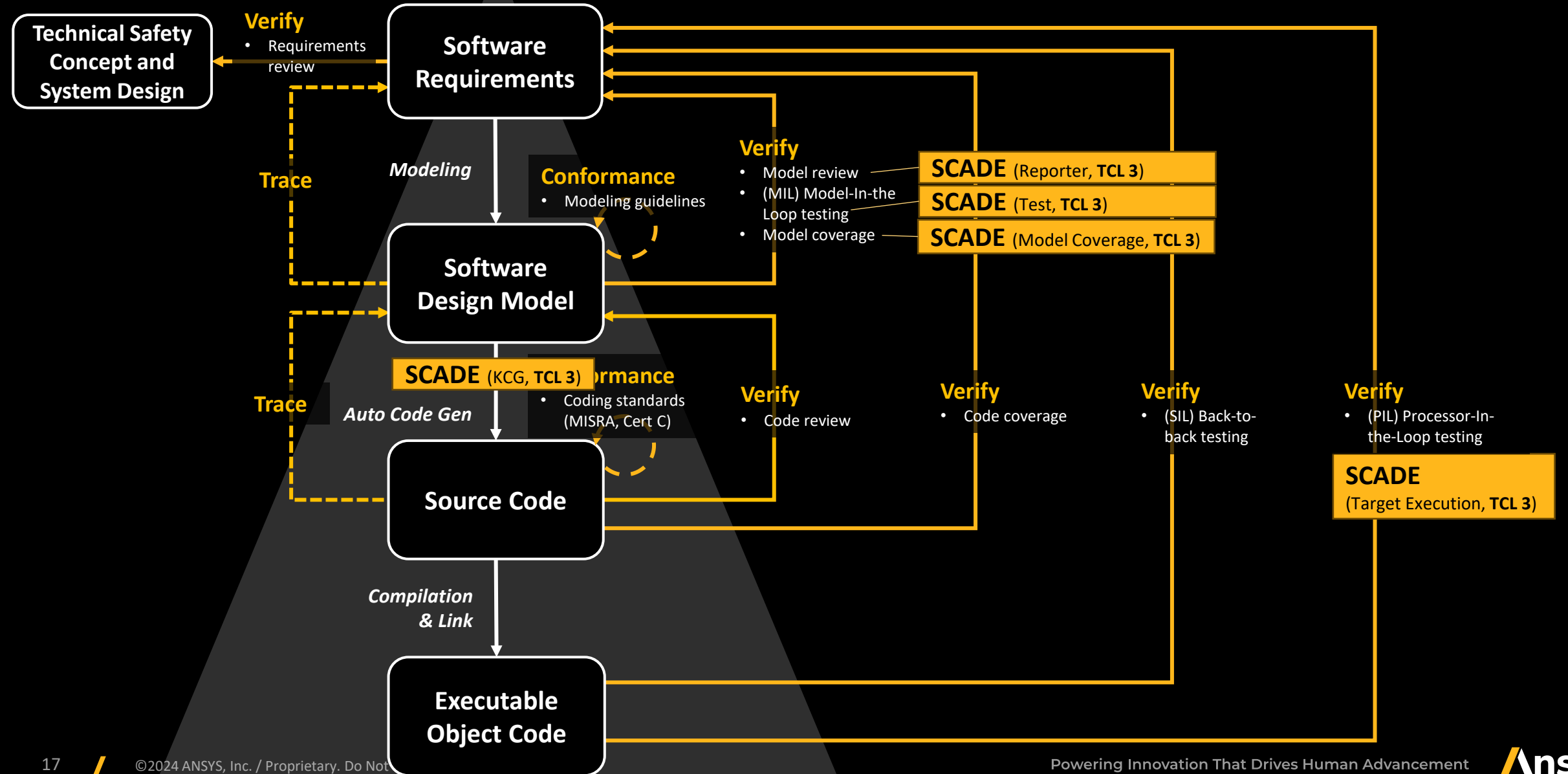


Benefits for the ISO 26262 process with Ansys SCADE

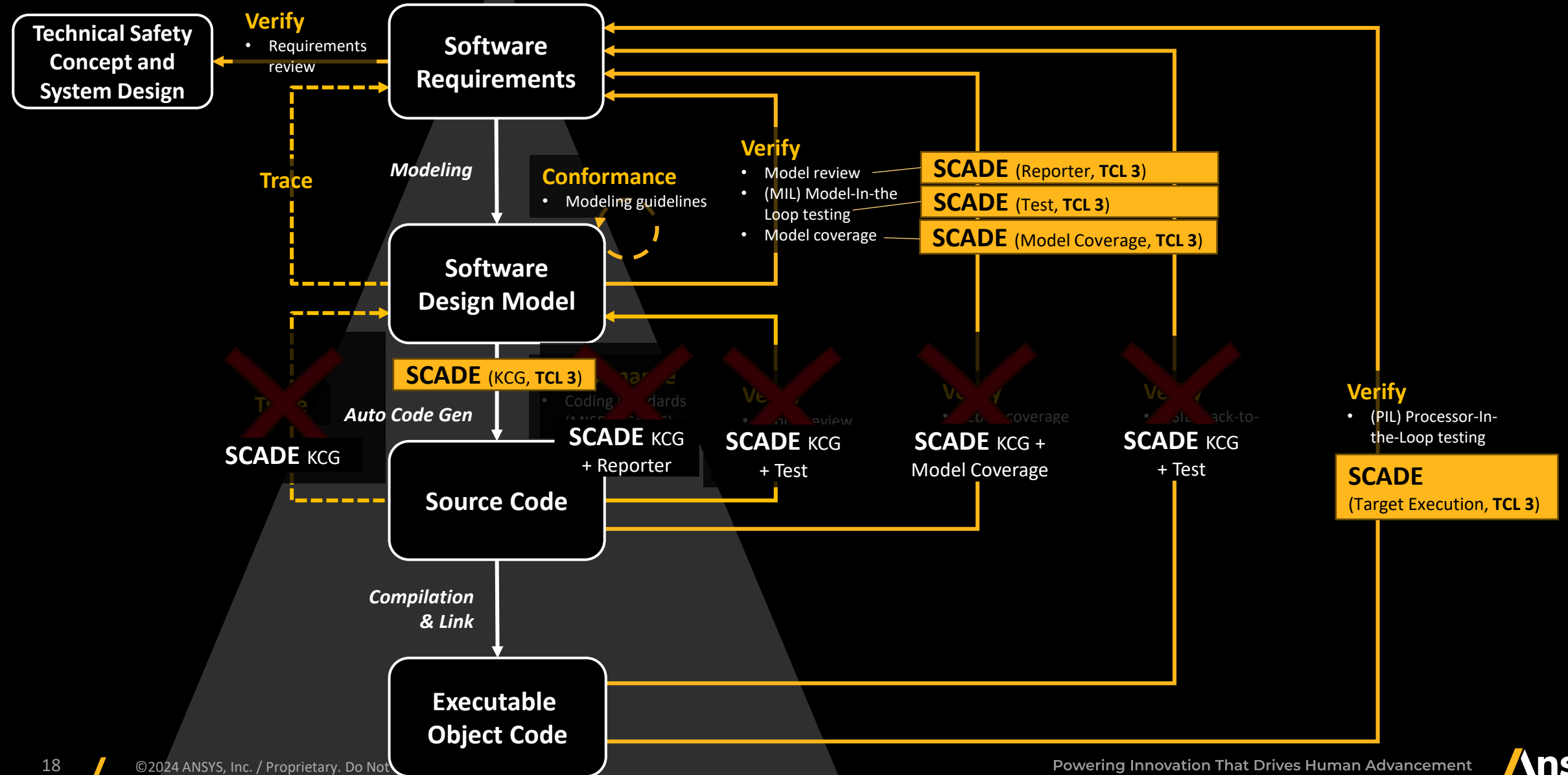
ISO 26262-6 Model-Based Software Design Workflow (Generic)



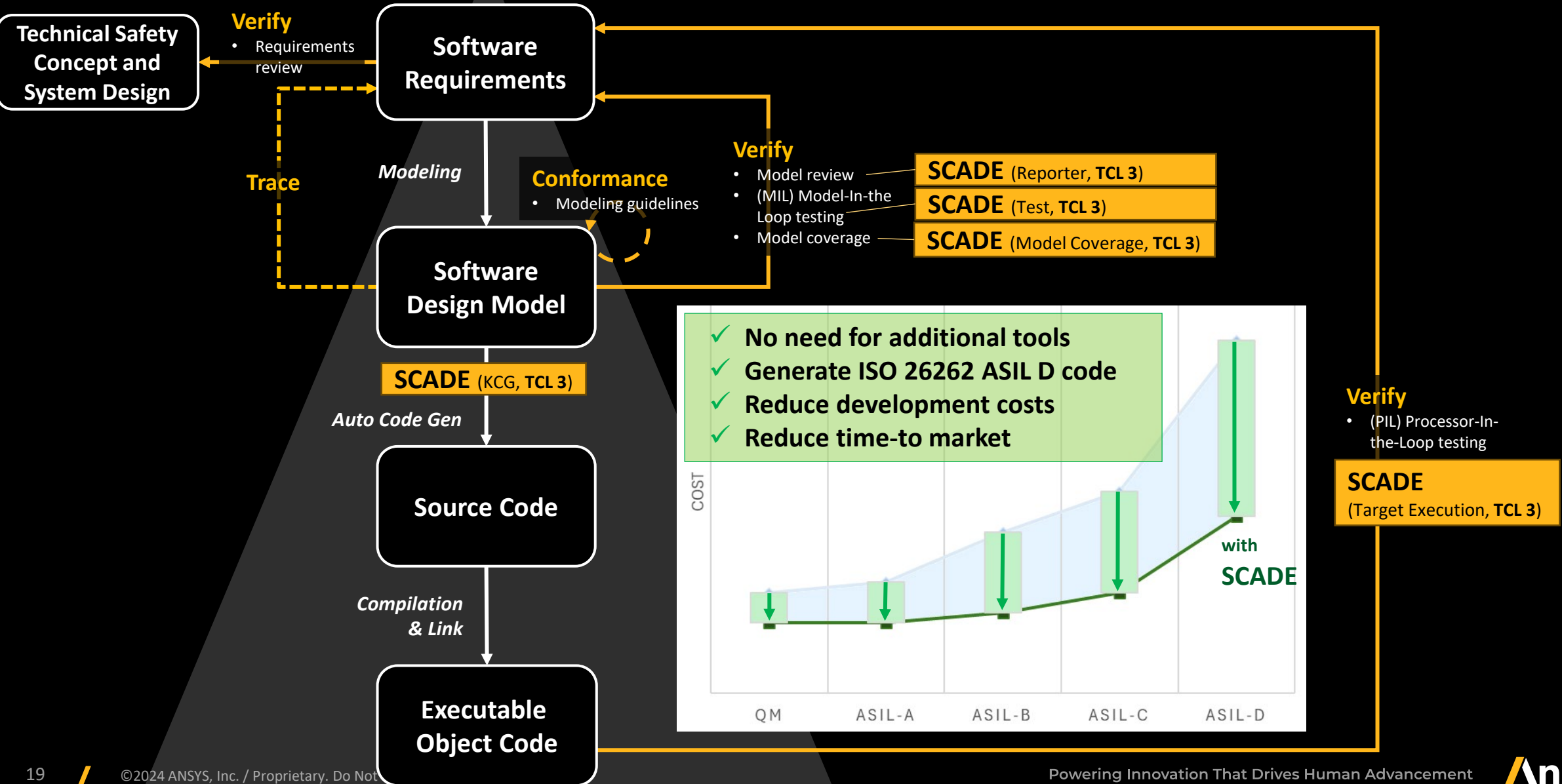
ISO 26262-6 Model-Based Software Design Workflow (with SCADE)



ISO 26262-6 Model-Based Software Design Workflow (with SCADE)



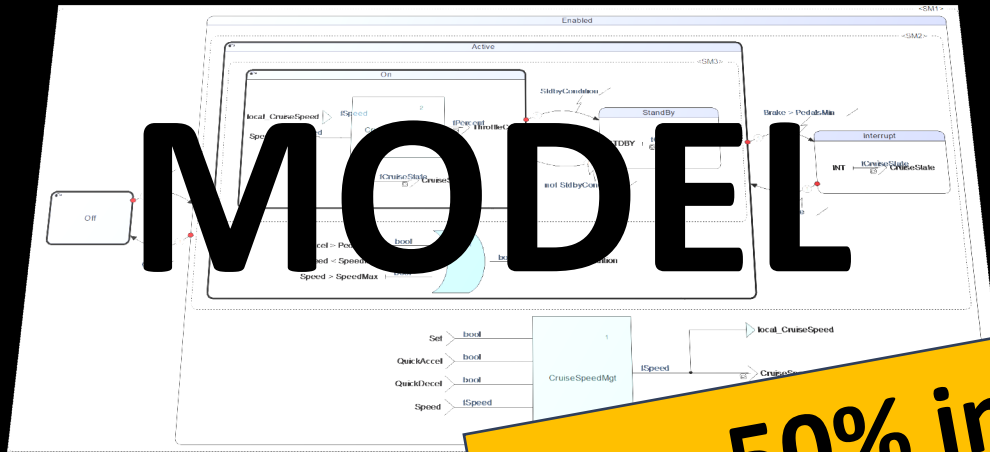
ISO 26262-6 Model-Based Software Design Workflow (with SCADE)





Summary

With **ANSYS** SCADE



MODEL

=

CODE

Save 50% in time and effort

```
/* Architecture::Regulation/ */  
void Regulation_Architecture(  
/* ECU_Command/ */  
tECU_cmd_Architecture *ECU_Command,  
/* AccelPedal/ */  
tPercent_Architecture AccelPedal,  
/* Speed/ */  
tVehicleSpeed_Architecture Speed,  
outC_Regulation_Architecture *outC)  
  
kcg_float32 ...  
/* SM1:Re ... L3/ */  
kcg_float ... L3_Regul_SM1  
/* SM1: *  
SSM_ST_S ... SM1-  
/* SM1: *  
kcg_t  
  
next) {  
SM1 :  
Command).Status == ON_Architecture;  
...act = SSM_st_Regul_SM1;  
else {  
SM1_state_act = SSM_st_NotRegul_SM1;  
}  
break;
```

**NO NEED
FOR SAFE
SUBSET**

**NO CODE
REVIEWS**

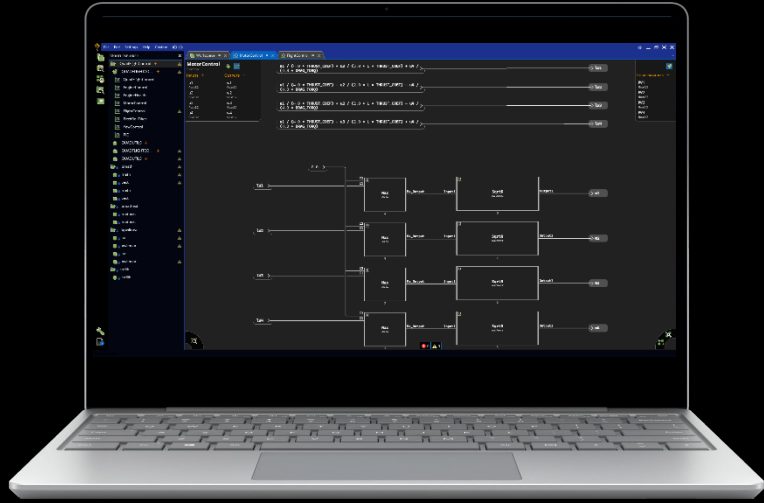
**NO SIL
BACK-TO-
BACK
TESTING**

**NO CODE
COVERAGE**



Coming up next...

Scade One / The next generation of SCADE



/ A **unified** environment, for all activities

Design | Debug | Generate | Test | Integrate

/ A **visual coding** experience

Efficient modeling | Auto-layout | On-the-fly-checks | User assistance

/ Improved **modeling** and **testing** capabilities

Better scalability | Simpler handling of array/matrices | Tests as models

/ **Democratizing** model-based development

Scade One Essential , a dedicated offering for non-certified embedded software

A Wider Scope of Applications!



In Every **Mission / Safety / Cost**
Critical Embedded System

... and many **more innovations** to come

Collaboration | Full V&V workflow | Qualification | Unified HMI/Logic